

# Automatic Learning of Simple and Accurate Fuzzy Rule Systems for Regression

Doctoral Meeting

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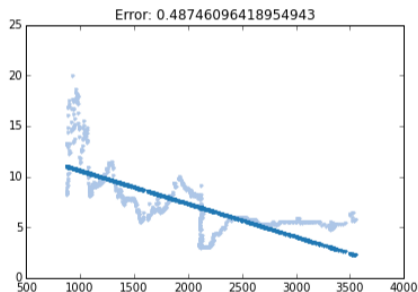
# Regression Problems

## Regression

- Predict a real-valued output using values of input variables

## Supervised learning

- Learn from labeled data
- Set of examples: pairs of input (vector) and output (real value)



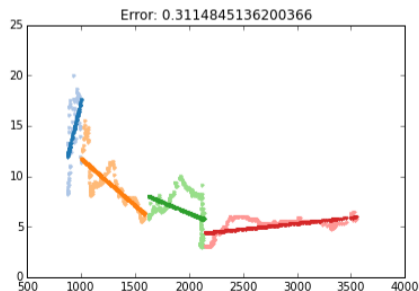
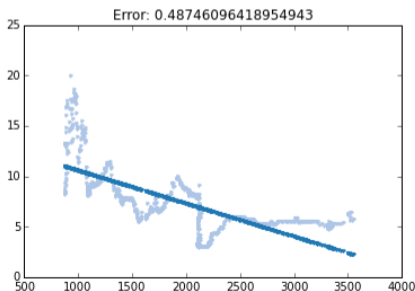
# Solving from the Scratch

Why from the scratch?

- Problems with no prior knowledge
- First approach useful for the expert

Divide and Conquer

- Split until local input-output relation is nearly linear



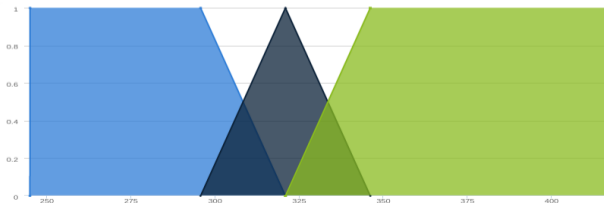
# Fuzzy Rules

## Fuzzy Sets

- An element  $x$  belongs to the set to some degree, e.g.  $\mu_A(x) = 0.7$ 
  - ▷ The surface of this building is High with degree 0.6

## Fuzzy Rule

- IF  $x$  is **A** THEN  $y$  is **B**
  - ▷ IF surface is **High** THEN cool load is **Very High**
- Meaning of A and B is provided by Fuzzy Sets



# TSK Fuzzy Rules

The output is a linear combination of the inputs

- IF  $x_1$  is **A** and  $x_2$  is **B** THEN  $y = \beta_0 + \beta_1 x_1 + \beta_2 x_2$ 
  - ▶ IF **surface is low** AND **wall area is high** THEN cool load = **0.2** surface + **1.7** wall
- Each rule has a different combination of the inputs

Inference

- Each rule is fired with different degree ( $\mu_r(x)$ ) depending on the input values
- Each rule estimates a different value for the output ( $\hat{y}_r$ )
- Final output is the weighed average:

$$\hat{y} = \frac{\sum_r \hat{y}_r \mu_r(x)}{\sum_r \mu_r(x)}$$

# Objective

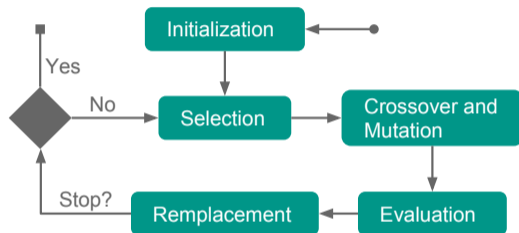
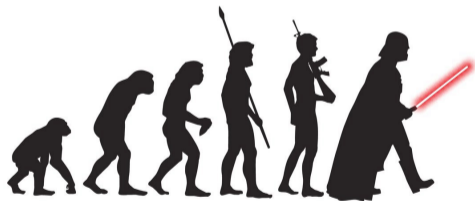
## Question

Is it possible to obtain **automatically simple** and **accurate** fuzzy rule models for regression problems without prior knowledge?

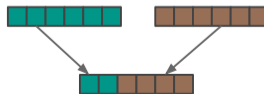
Automatic Learn	Simple	Accurate
Fuzzy partitions	Few labels	Linear regions
Rule set	Low number of rules	Precise rules
Weights of consequents	Regularization	Regularization

# Evolutionary Algorithms

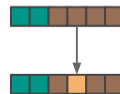
Works like natural evolution



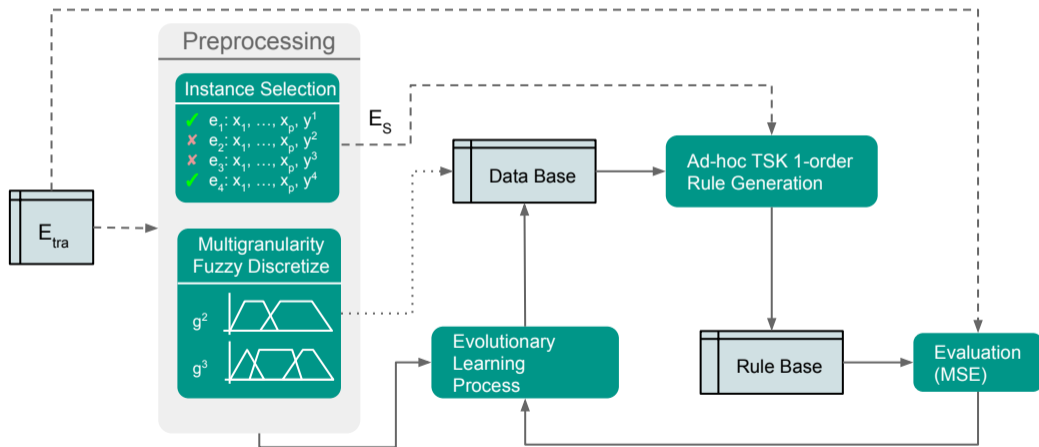
Crossover



Mutation



# FRULER





# Instance Selection

Based on conditional nearest neighbor

- Nearest example with same class
- Nearest example with different class

Two phases:

- Class conditional
  - ▷ Enlarge margin between “classes”
- Thin-out
  - ▷ Removes examples not important for the decision boundary

## Adapt to Regression

- Discretization of the output
  - ▷ Kernel Density Estimation
  - ▷ Local minimum = split points
- Error measure in 1-NN for regression
  - ▷ More precision
- Relax the stopping criteria, allowing iterations without improvement
  - ▷ Error in regression varies more than accuracy in classification

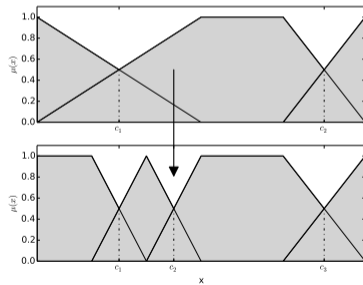
# Multi-Granularity Fuzzy Discretization

Obtains several partition levels, from 1 label to N labels

- There is no information about how many labels are needed

For each input variable

- Searches the split points iteratively
- Only a new split point is added at each step, obtaining two new intervals
- Selects the split point that maximizes the linear relation in each resulting interval
- Stops when BIC worsens for a consecutive number of iterations
- Fuzzify the crisp intervals relaxing the frontiers

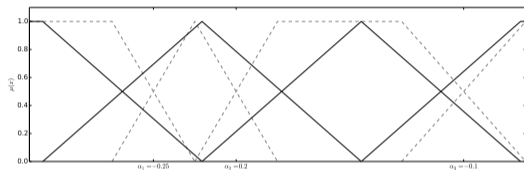


# Evolutionary Algorithm

## Individual Codification

The split points are suboptimal

- Allow a small lateral displacement



Parameters to learn:

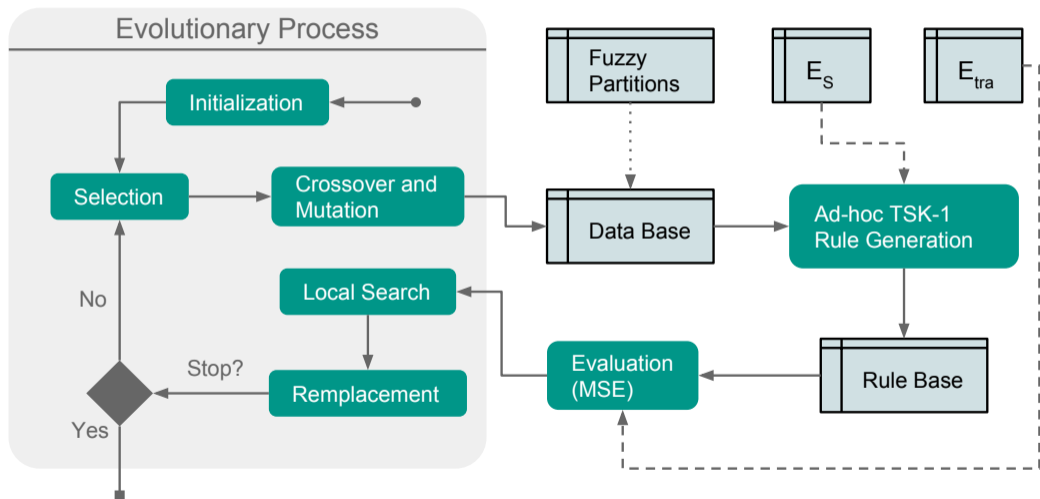
- Granularity level in each input
- Displacement of each split point

Codification

- $[g_1, g_2, \dots, g_p]$
- $[[s_1^1, \dots, s_1^n], \dots, [s_p^1, \dots, s_p^m]]$

# Evolutionary Algorithm

## Operators



# TSK Rule Base Generation

## Antecedents

- 1 Apply the displacements
- 2 Wang & Mendel: obtain the rule set that covers all examples

## Consequents

- Learn all consequents at once
- Elastic-Net (L1+L2):  $\hat{\beta} = \min_{\beta} \frac{1}{2} \sum_i (y - \beta x_i)^2 + \alpha \lambda \sum_j |\beta_j| + (1 - \alpha) \lambda \sum_j \beta_j^2$
- Solve with Stochastic Gradient Descent
  - ▷  $\alpha = 0.95$ : behaves like L1 but with low weights like L2
  - ▷ Learning rate and regularization parameter  $\lambda$  with fast grid Search

# Comparison with State-of-the-art

## Precision

algorithms	FRULER	FS <sub>MOGFS</sub> <sup>e</sup> +TUN <sup>e</sup>	L-METSK-HD <sup>e</sup>	A-METSK-HD <sup>e</sup>
ELE1	2.012	<b>1.954</b>	1.925	2.022
PLA	1.219	1.194	1.218	<b>1.136</b>
QUA	0.0181	<b>0.0178</b>	0.019	0.0181
ELE2	6,729	10,548	20,095	<b>3,192</b>
FRIE	<b>0.731</b>	3.138	3.084	1.888
MPG6	<b>3.727</b>	4.562	4.469	4.478
DELAİL	1.458	1.528	1.621	<b>1.402</b>
DEE	<b>0.080</b>	0.093	0.095	0.103
DELELV	1.045	1.086	1.119	1.031
ANA	0.008	<b>0.003</b>	0.006	0.004
MPG8	<b>4.084</b>	4.747	5.61	5.391
ABA	2.393	2.509	2.581	<b>2.392</b>
CON	<b>20.598</b>	32.977	38.394	23.885
STP	<b>0.353</b>	0.912	0.78	0.387
WAN	<b>0.888</b>	1.635	1.773	1.189
WIZ	<b>0.663</b>	1.011	1.296	0.944
FOR	<b>2,214</b>	2,628	4,633	5,587
MOR	<b>0.007</b>	0.019	0.028	0.013
TRE	<b>0.027</b>	0.044	0.052	0.038
BAS	305,777	<b>261,322</b>	320,133	368,820
CAL	2.110	2.95	2.638	<b>1.71</b>
MV	0.083	0.158	0.244	<b>0.061</b>
HOU	<b>8.005</b>	9.4	10.368	8.64
ELE	<b>2.934</b>	9	8.9	7.02
CA	<b>4.634</b>	5.216	5.88	4.949
POLE	110.898	102.816	150.673	<b>61.018</b>
PUM	0.367	0.292	0.594	<b>0.287</b>
AIL	<b>1.404</b>	2	1.822	1.51

Best in 15 of 28 datasets

# Comparison with State-of-the-art

## Number of rules

algorithms	FRULER	FS <sub>MOGFS</sub> <sup>e</sup> +TUN <sup>e</sup>	L-METSK-HD <sup>e</sup>	A-METSK-HD <sup>e</sup>
ELE1	<b>4.1</b>	8.1	15	11.4
PLA	<b>1.4</b>	18.6	23	19.2
QUA	7.8	<b>3.2</b>	35.9	18.3
ELE2	<b>4.3</b>	8	59	36.9
FRIE	<b>8.0</b>	22	95.1	66
MPG6	<b>13.7</b>	20	99.6	53.6
DELAİL	<b>2.5</b>	6.2	98.3	36.8
DEE	<b>7.9</b>	18.3	96.4	50.6
DELELV	<b>5.8</b>	7.9	91	39.1
ANA	<b>3.9</b>	10	48.9	33.3
MPG8	<b>12.7</b>	23	98.7	64.2
ABA	<b>4.5</b>	8	42.4	23.1
CON	<b>8.9</b>	15.4	96.5	53.7
STP	42.4	<b>23</b>	100	66.4
WAN	<b>5.6</b>	8	91.1	48
WIZ	<b>8.9</b>	10	55.4	29.1
FOR	<b>5.6</b>	10	93.7	40.6
MOR	7.9	7	40.9	27.2
TRE	<b>4.5</b>	9	42.8	28.1
BAS	<b>6.2</b>	17	95.7	59.8
CAL	15.4	<b>8.4</b>	99.8	55.8
MV	<b>6.0</b>	14	76.4	56.5
HOU	12.1	<b>11.7</b>	68.9	30.5
ELE	<b>5.4</b>	8	76.4	34.9
CA	<b>7.1</b>	14	71.3	32.9
POLE	40.8	<b>13.1</b>	100	46.3
PUM	<b>7.8</b>	17.6	87.5	63.3
AIL	<b>8.5</b>	15	99.1	48.4

Best in 22 of 28 datasets

# Statistical Analysis

Algorithm	Ranking
FRULER	1.714
A-METSK-HD <sup>e</sup>	2.036
FS <sub>MOGFS</sub> <sup>e</sup> +TUN <sup>e</sup>	2.786
L-METSK-HD <sup>e</sup>	3.464
Holm p-value	0.079

Table: Precision test

Algorithm	Ranking
FRULER	1.214
FS <sub>MOGFS</sub> <sup>e</sup> +TUN <sup>e</sup>	1.786
A-METSK-HD <sup>e</sup>	3
L-METSK-HD <sup>e</sup>	4
Holm p-value	$< 1E - 4$

Table: Complexity test

Tests performed using:





# Example of Learned Model

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**TSKView**

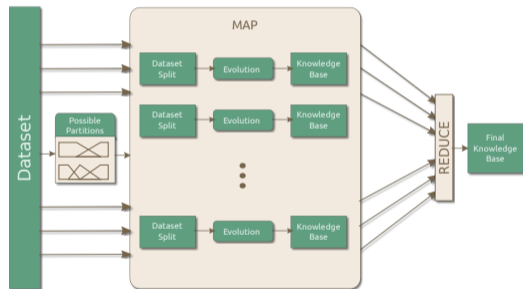
# Scaling FRULER

## Computational time

- Less than 1 hour for small-medium datasets
- From 2h to 30h for large datasets

## More Divide and Conquer:

- 1 Split dataset into Mappers
- 2 Subset of input variables for each split
- 3 Use FRULER for each split
- 4 Aggregate the resultant TSK Fuzzy Rule bases



# Conclusions

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- FRULER learns simple and accurate TSK Fuzzy Rule Bases without prior knowledge
- Uses two general-purpose methods:
  - ▷ Instance Selection for regression
  - ▷ Non-uniform multi-granularity fuzzy discretization
- Automatic generation of TSK Fuzzy Rules from fuzzy partitions
  - ▷ Elastic-Net for low overfitting
  - ▷ Stochastic Gradient Descent for fast learning
- Compared with other three state-of-the-art approaches
  - ▷ High accuracy
  - ▷ Lower number of rules
  - ▷ Linguistic data base

**Thank you!**

**Questions?**

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